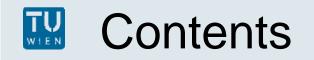




The Planetary Motor Design and control of a novel multi-rotor structure

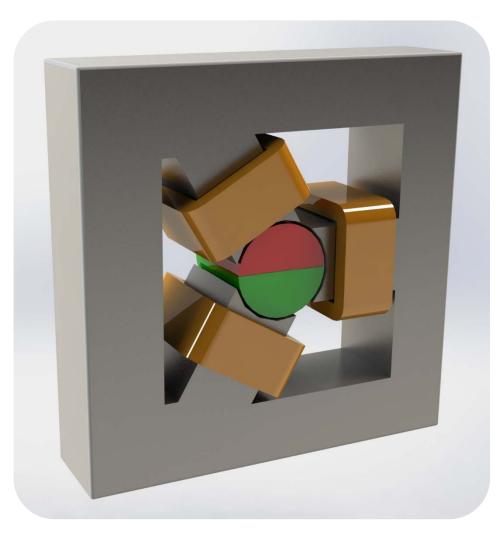
Manfred Schrödl Andreas Brunner Institute of Energy Systems and Electrical Drives Technische Universität Wien A3PS Nov. 2017



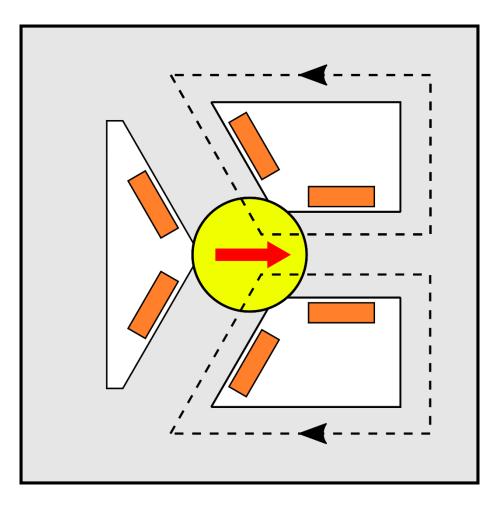
- Deriving the topology of the Planetary Motor
- Electrical equivalent circuit
- Functional prototype
- Control strategy
- Sensorless INFORM® method
- Applications
- Future work

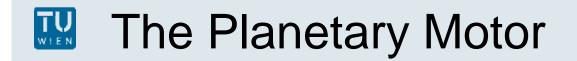
W The Planetary Motor

- 3-phase motor
- 3 single coils
- 2-pole PM rotor

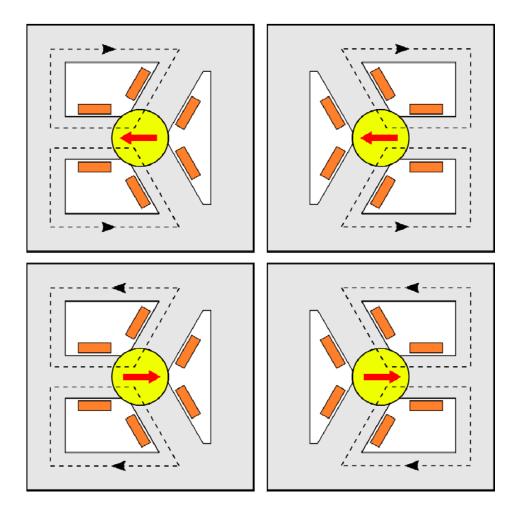


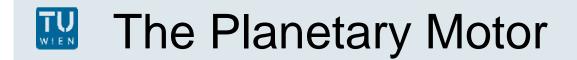




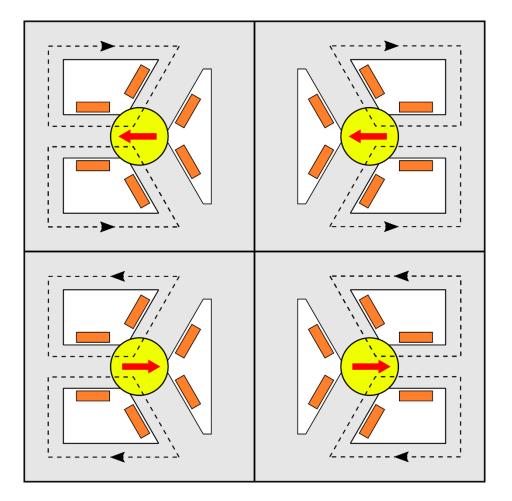


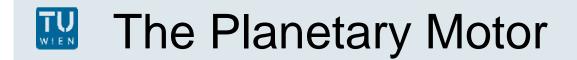
• Arrange 4 equivalent motors symmetrically



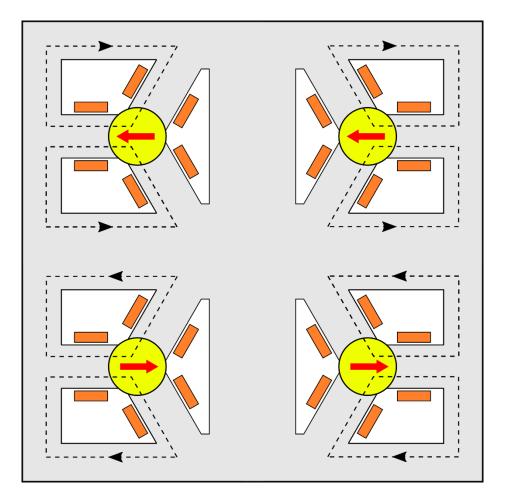


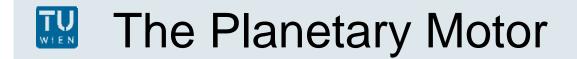
• Combine into single structure



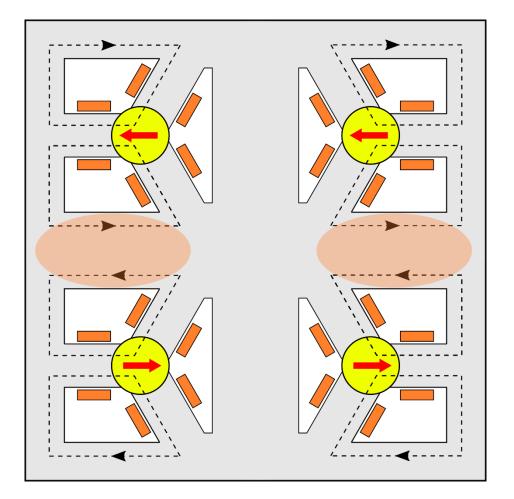


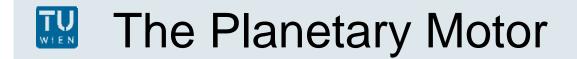
• Combine into single structure



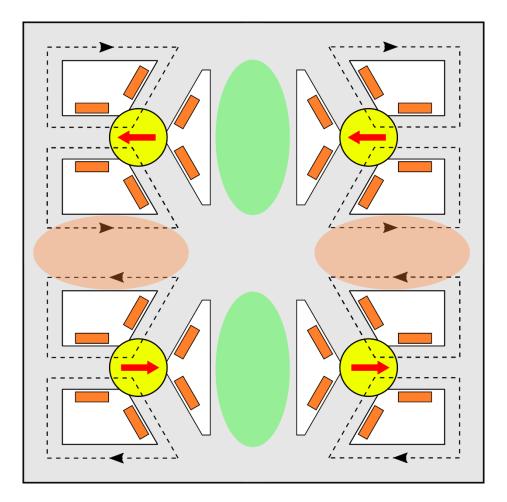


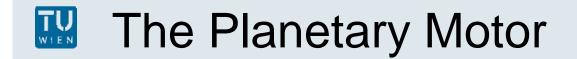
• Areas of zero net flux



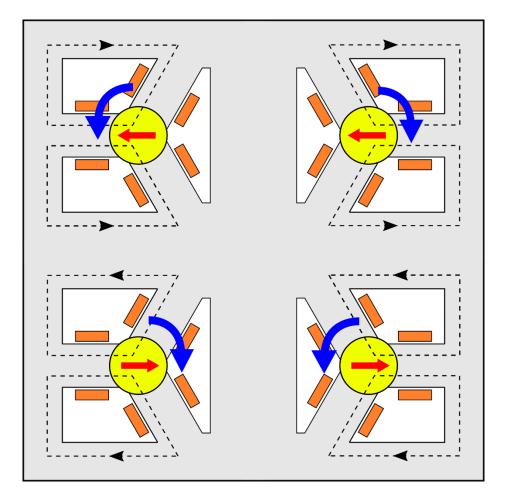


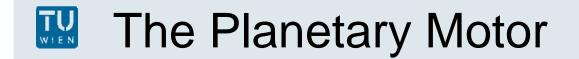
• Areas of zero net flux



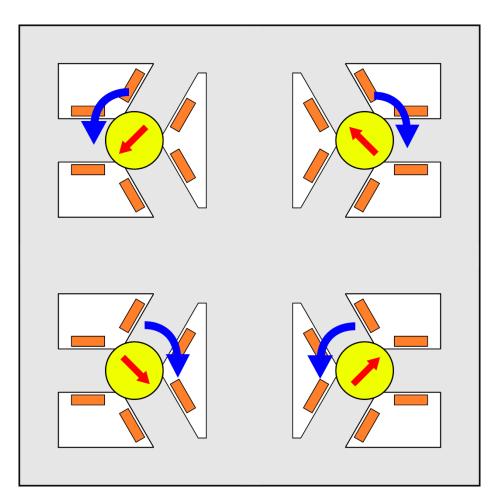


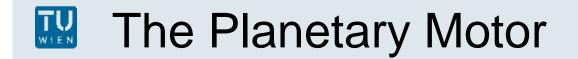
Rotors turn in opposite directions



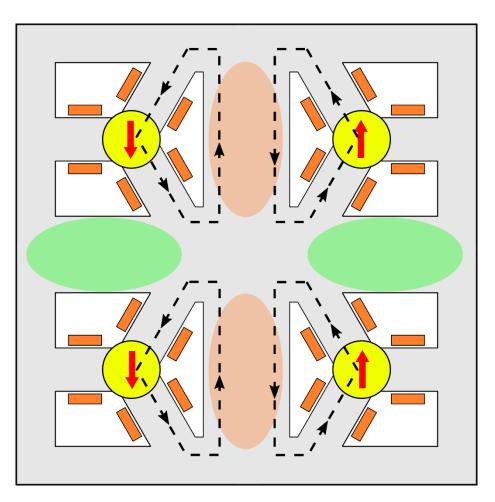


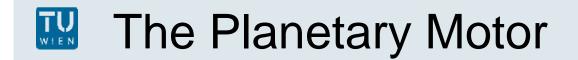
Rotors turn in opposite directions



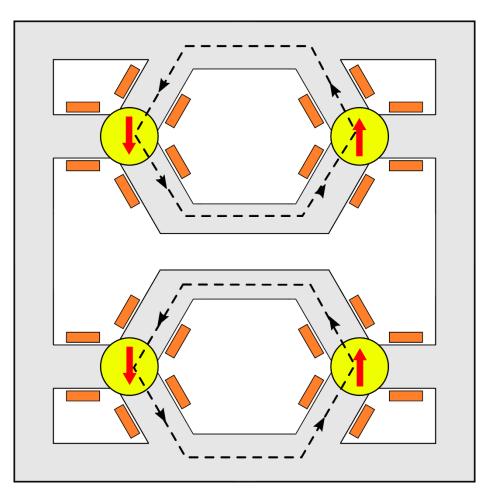


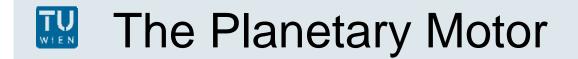
• After 90deg: same areas with zero net flux

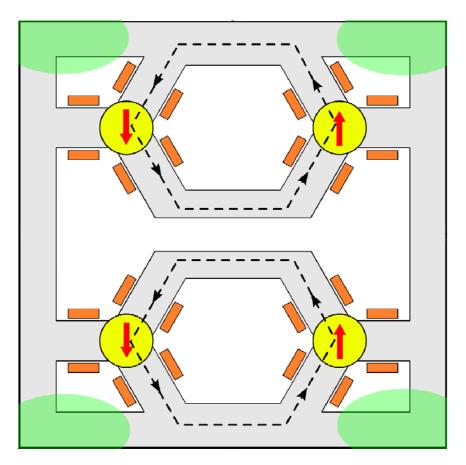


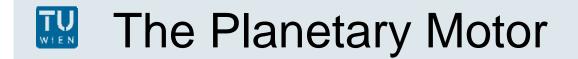


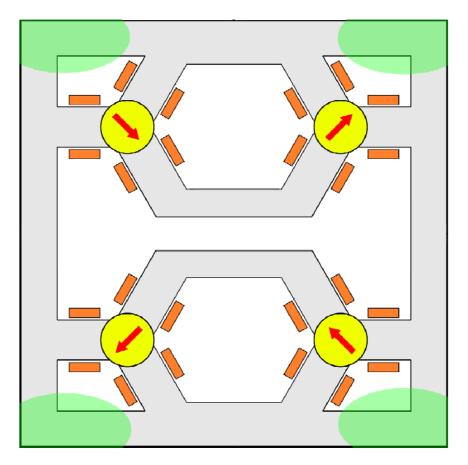
• Omit magnetically inactive parts:

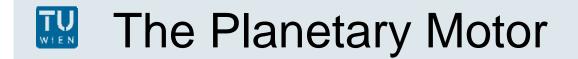


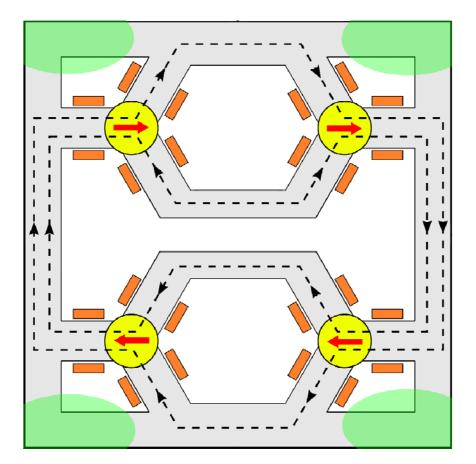


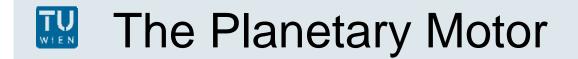


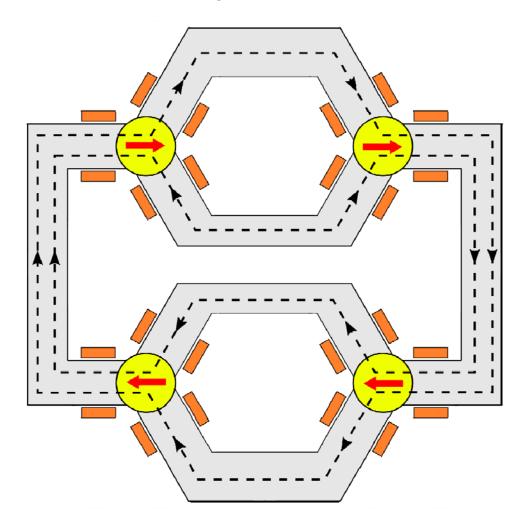












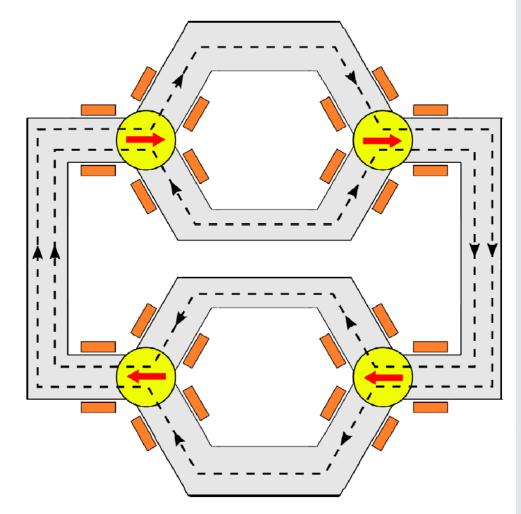
The Planetary Motor

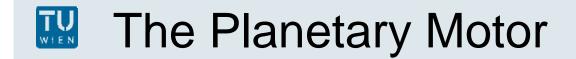
• Omit magnetically inactive parts:

Reduced

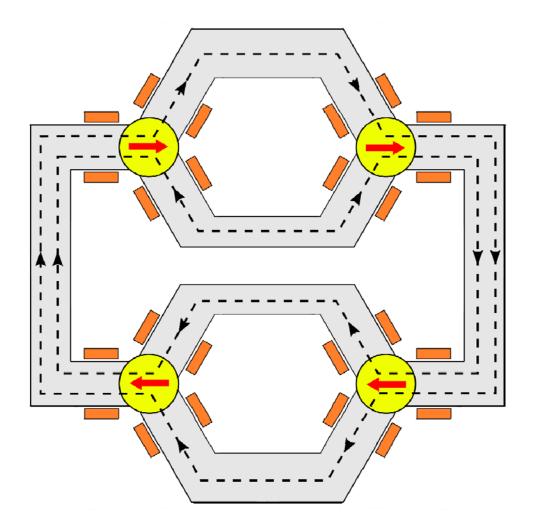
- Active mass
- Motor volume
- Iron losses

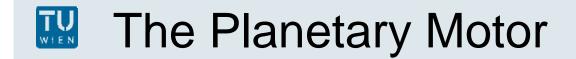
Same power as 4 combined single motors



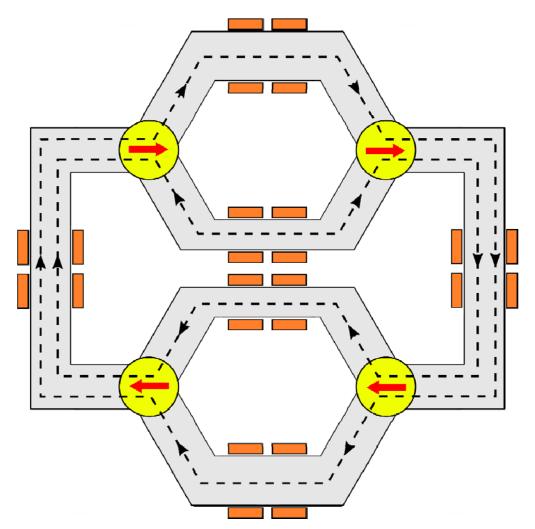


• Combine coils

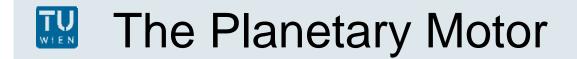




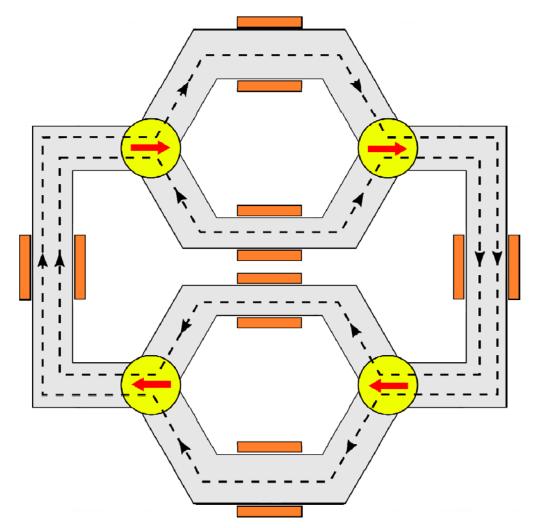
• Combine coils

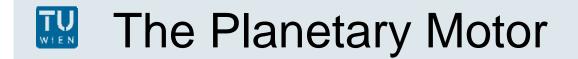


20

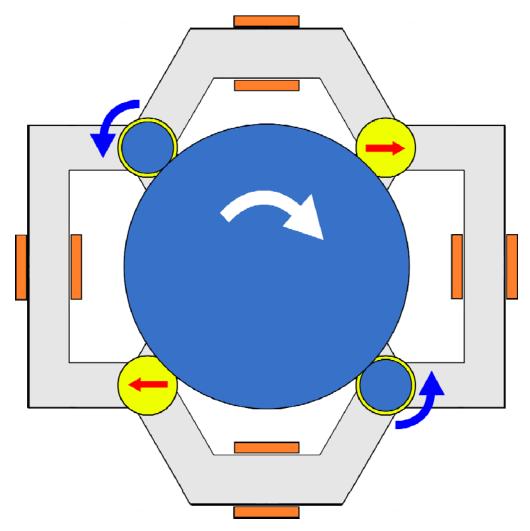


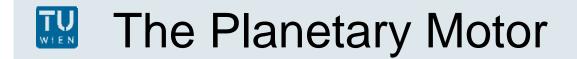
• Combine coils: 12 coils \rightarrow 6 coils



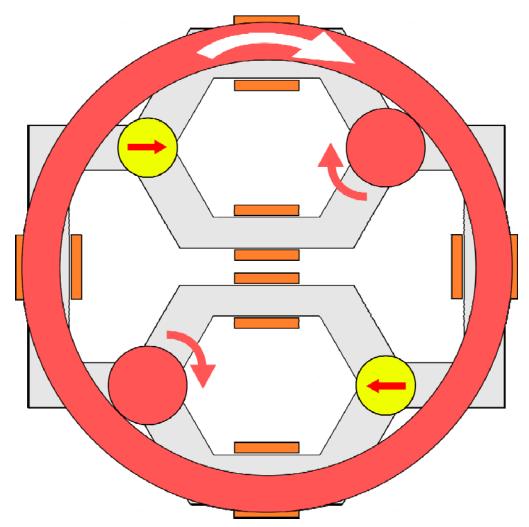


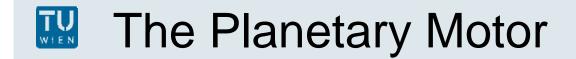
• Integrated gear: sun gear



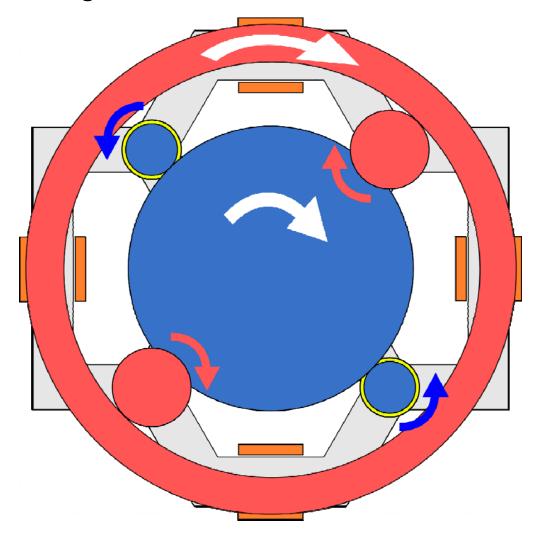


• Integrated gear: ring gear



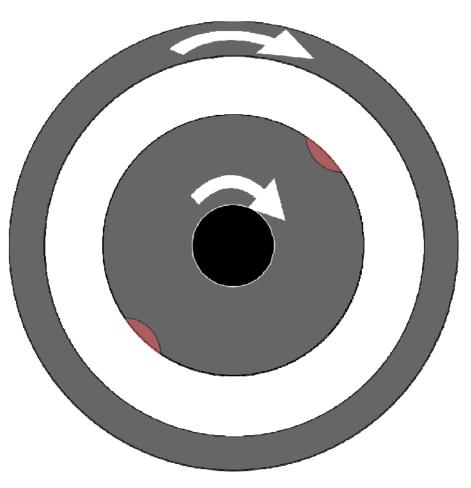


• Integrated gear



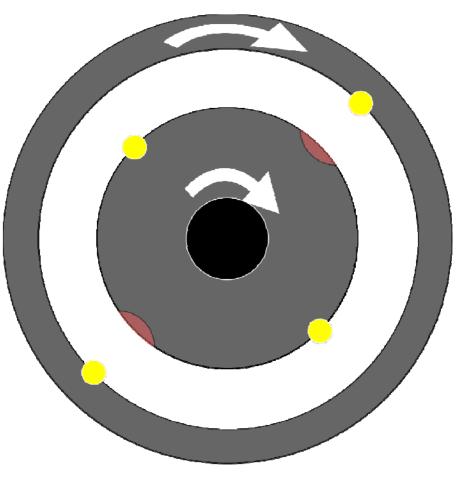
The Planetary Motor

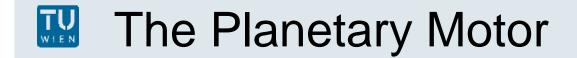
- Integrated "planetary gear"
 - Sun gear and ring gear rotate at same speed → mechanical link for combined output power

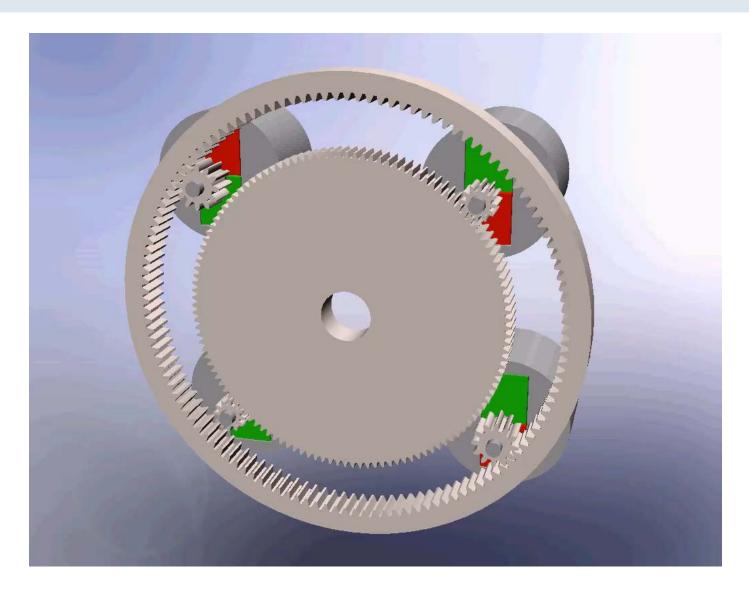


The Planetary Motor

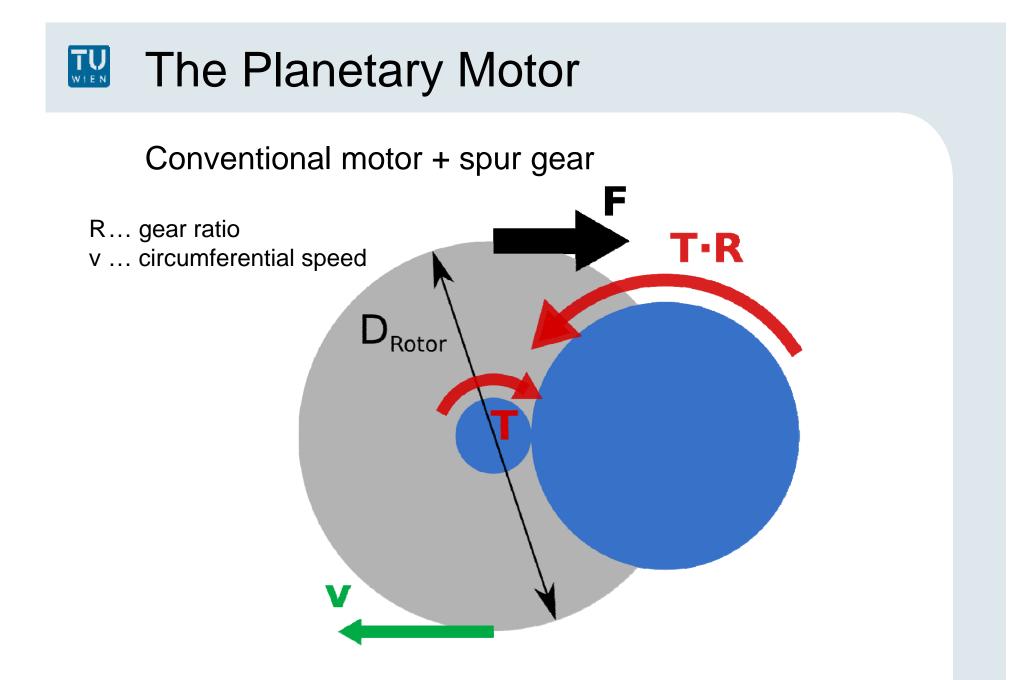
- Integrated "planetary gear"
 - One point of contact for each gear (instead of two)
 - Gear ratios typ. 10:1

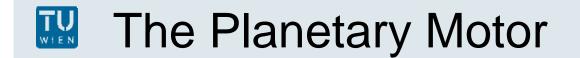


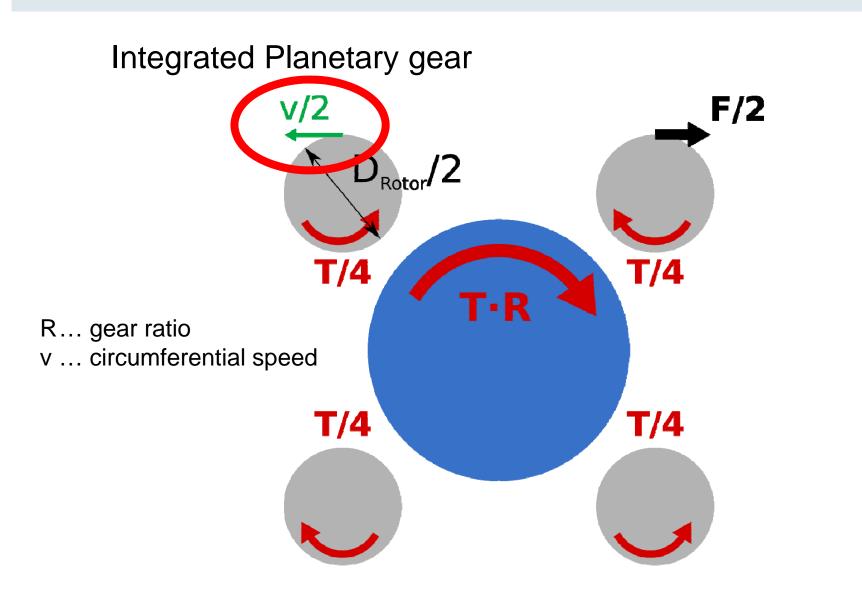




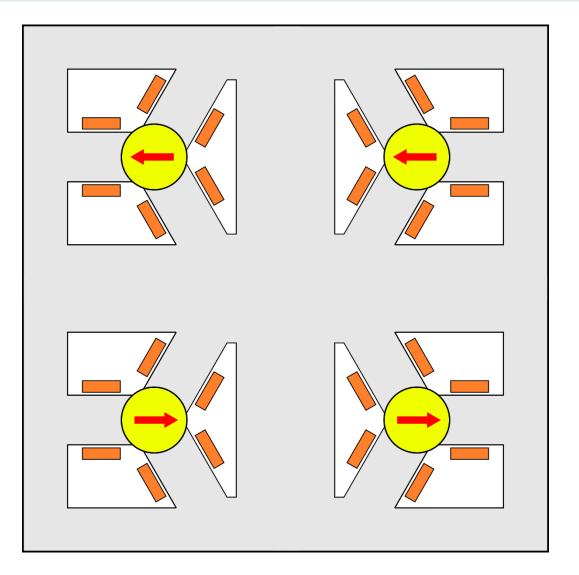
9.11.2017 – A3PS 2017





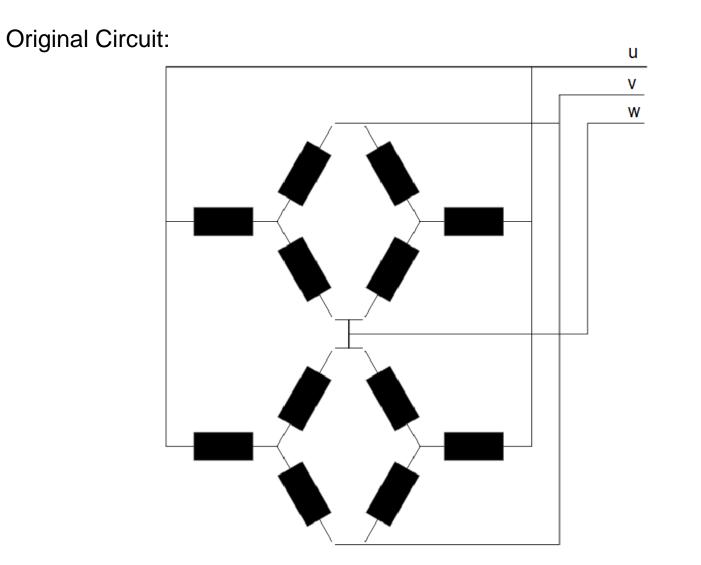




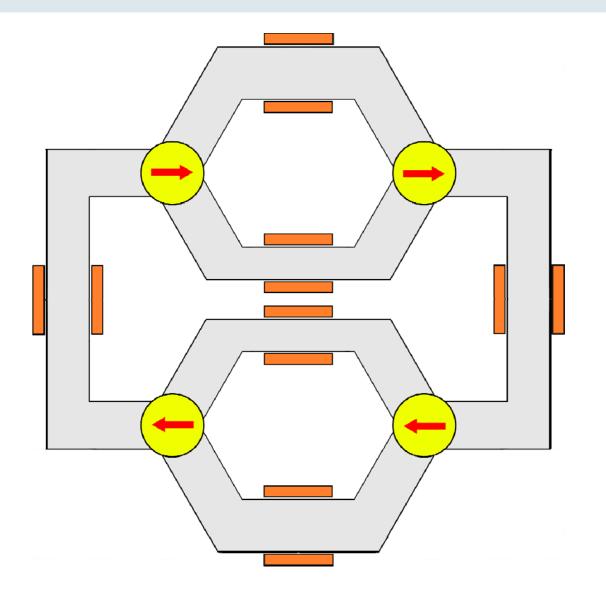


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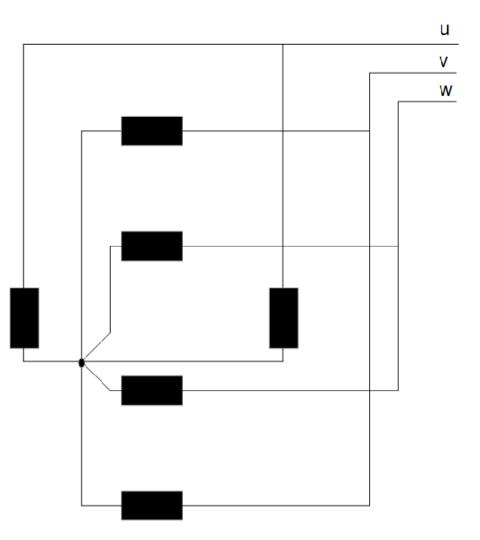


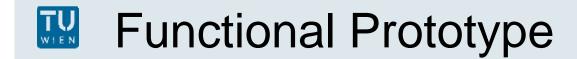


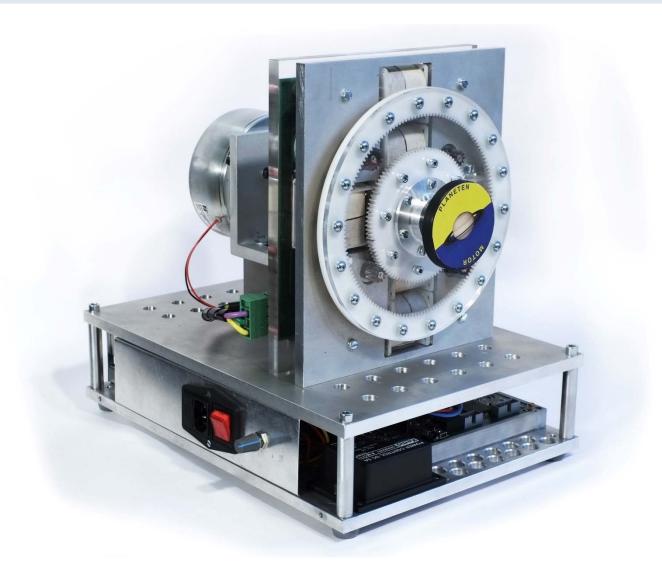


Reduced Circuit:

- 3-phase inverter
- Star or delta connection



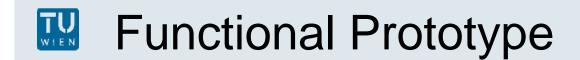




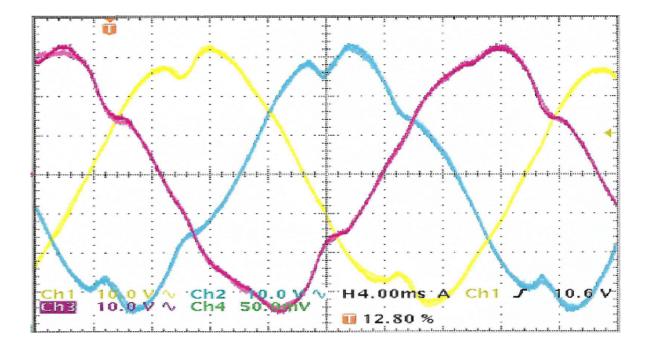
Even Functional Prototype

- 4 rotors and 3-phase stator winding
- 6 concentrated coils
- Gear ratio 10:1
- Sensorless control (INFORM / EMF)
- Connection of all coils on the rear side of the motor
 - Simple assembly

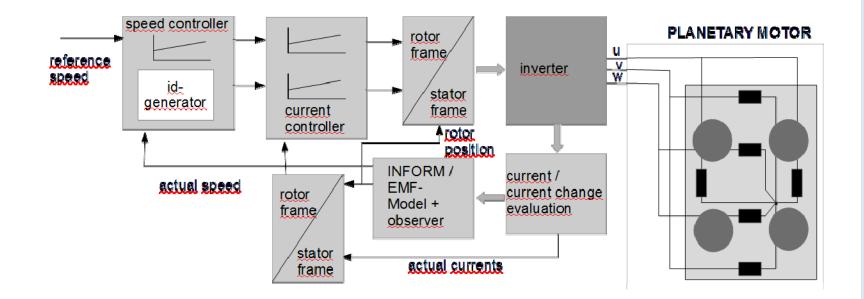


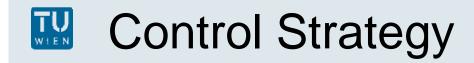


Terminal voltages at 200rpm on output shaft:



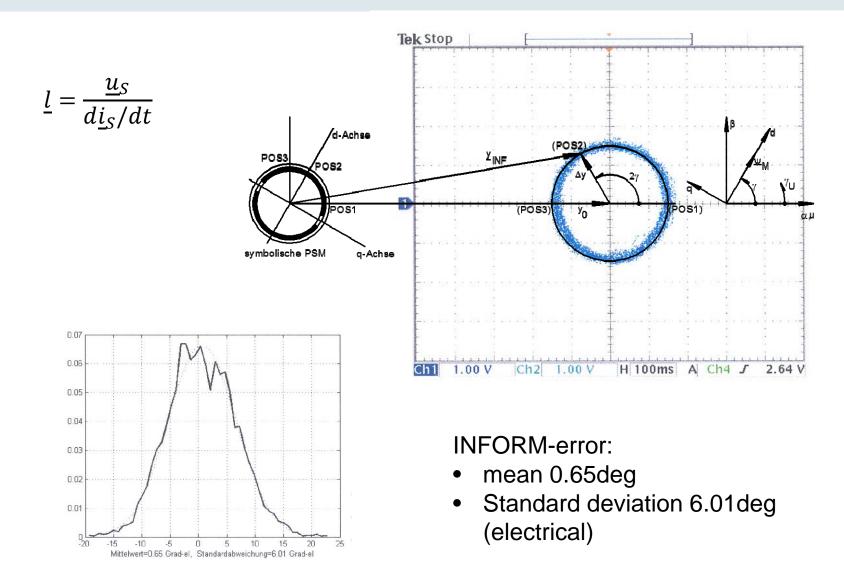


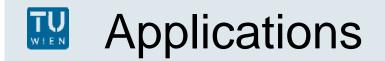




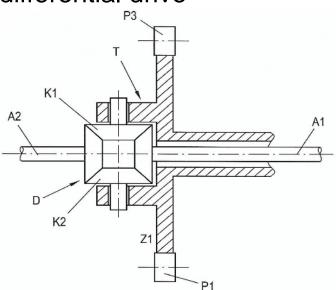
- High-speed range (> 10% rated speed): EMF-method
 - Based on induced voltage
 - State of the art
- Low-speed range and standstill: INFORM® method
 - Based on inductance differences
 - Already used in series applications

INFORM® Method





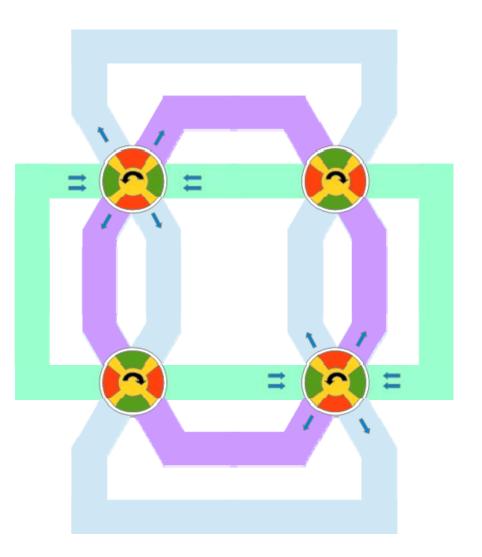
- Electric vehicle axle drive
 - Integrated gear box
 - Hollow central motor shaft \rightarrow differential drive
- Wheel-hub motor
- Low speed / high torque
- Wind power



PLANETARY MOTOR with differential gear D (housing T, bevel wheels K1, K2), functionally combined with sun wheel Z1. Planets P1, P3 (shown without connected rotors of the electrical part). Half axes A1, A2, connected to driving wheels

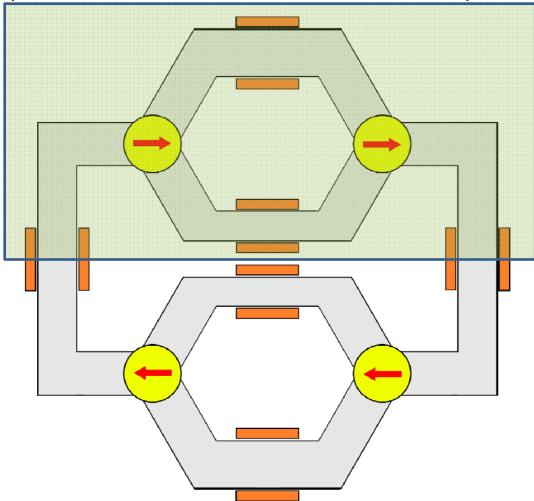


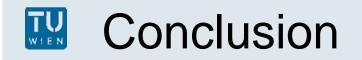
- 4-pole rotors
- 12 coils





6 rotors (series connection of 3 elements)





- 1 rotor → 4 rotors: half circumferential speed at same power
- Integrated transmission
 - Low speed / high torque applications
- Simple assembly
 - Concentrated coils
 - Integrated coil connections and power electronics on rear side possible
- Standard 3-phase inverters
 - Sensorless control





Thank you for your attention

TU Wien offers cooperation Please contact us!

Manfred.schroedl@tuwien.ac.at